Optimal Control for Entangling Quantum Gates

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the quantum optimal control problem

quantum technology

steer quantum system in some desired way



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quantum technology

steer quantum system in some desired way



examples:

. . .

- photo-chemistry: form atomic bonds
- medical imaging: orient nuclear spin for max resolution
- **quantum networks:** prepare non-classical states
- quantum computing: apply logical operation ("gate")



$$\left|\Psi\right\rangle = \alpha_{0}\underbrace{\left|0\dots1\right\rangle}_{\mathsf{N \ qubits}} + \dots + \alpha_{\mathsf{2^{N}}}\left|1\dots1\right\rangle$$

reduce to two-qubit gates: 4×4 matrix



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$$|\Psi
angle
ightarrow \hat{\mathbf{0}} |\Psi
angle \; , e.g.$$

 $\hat{\mathbf{0}} = egin{pmatrix} 1 & 0 & 0 & 0 \ 0 & 1 & 0 & 0 \ 0 & 0 & 0 & 1 \ 0 & 0 & 1 & 0 \end{pmatrix}$



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reduce to two-qubit gates: 4×4 matrix

Implementations:

- trapped atoms
- superconducting circuits
- NV centers
- quantum dots

...

logical subspace



logical subspace



logical subspace embedded in larger total Hilbert space!

analytical:

- geometric control low dimension
- adiabatic schemes (e.g. STIRAP) slow
- open quantum systems? noise? fundamental limits?

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minimize functional J_T

e.g.
$$J_T = 1 - \frac{1}{d^2} \sum_{k=1}^d \left| \left\langle \Psi_k^{\text{tgt}} \middle| \Psi_k(T) \right\rangle \right|^2$$

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numerical:

$$|\Psi^{(0)}\rangle = t_{0} t_{1} t_{2} t_{3} t_{4} t_{5} t_{6} T$$

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e.g.
$$J_{\mathcal{T}} = 1 - \frac{1}{d^2} \sum_{k=1}^{d} \left| \left\langle \Psi_k^{\text{tgt}} \middle| \Psi_k(\mathcal{T}) \right\rangle \right|^2$$

 \Rightarrow iterative scheme

propagation

iteration

 $\Delta \epsilon$

Optimization Methods











only evaluate fig. of merit J_T ■ any J_T



- any J_T
- good for small number of control parameters





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Nelder-Mead simplex:







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easy to use: scipy.optimize, Matlab, ...

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a control parameters: $\epsilon_i = \epsilon(t_i)$ for all points on time grid **a** $J_T \sim \langle \Psi^{\text{tgt}} | \Psi(T) \rangle = \left\langle \Psi^{\text{tgt}} | \hat{\mathbf{U}}_{nt} \dots \hat{\mathbf{U}}_1 | \Psi_0 \right\rangle$ **a** $\frac{\partial J_T}{\partial \epsilon_i} = \underbrace{\left\langle \Psi^{\text{tgt}} \middle| \hat{\mathbf{U}}^{\dagger}(t_i, T) \right\rangle}_{\langle \Psi_{bw} |} \underbrace{\frac{\partial \hat{\mathbf{U}}_i}{\partial \epsilon_i}}_{|\Psi_{fw} \rangle}_{|\Psi_{fw} \rangle}$

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update scheme

$$\begin{split} \Delta \epsilon_{i} \sim \frac{\partial J_{T}}{\partial \epsilon_{i}} \sim \left\langle \Psi^{\mathsf{bw}} \middle| \frac{\partial \hat{\mathbf{U}}_{i}}{\partial \epsilon_{i}} \middle| \Psi^{\mathsf{fw}} \right\rangle \\ |\Psi^{(0)} \rangle & \stackrel{|}{\underset{t_{0}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|}}{\overset{|$$

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update scheme

Khaneja et al. J. Magnet. Res. 172, 296 (2005) library implementation: L-BFGS-B

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$$\Delta \epsilon(t) \sim \langle \chi^{\mathsf{bw}} | \frac{\partial \hat{\mathsf{H}}}{\partial \epsilon} | \Psi^{\mathsf{fw}} \rangle$$
$$|\Psi^{(0)} \rangle \underbrace{\stackrel{\epsilon^{(1)}}{\stackrel{\downarrow}{\overset{\downarrow}{\overset{\downarrow}{\overset{\bullet}{\overset{\bullet}}}}}}_{t_0} \epsilon^{(0)}}_{t_0} | \chi \rangle = \frac{\partial J_T}{\langle \Psi |}$$

Reich et al. J. Chem. Phys. 136, 104103 (2012)



GRAPE



- sequential update
- continuous \rightarrow discrete
- guaranteed monotonic convergence
- *J_T* only in boundary condition

- concurrent update
- inherently discrete
- parametrization through chain rule

Applications
the quantum speed limit

progressively decrease gate duration

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- QSL is reached when objective can no longer be reached

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example: optimization of entangling and local gates in superconducting transmon qubits



robustness to classical fluctuations



robustness to classical fluctuations



noise sources: fluctuation of Rydberg level, field amplitude

robustness to classical fluctuations



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ensemble optimization

simultaneously optimize over multiple copies of the system with different noise realizations





 \Rightarrow Goerz, Halperin, Aytac, Koch, Whaley. PRA 90, 032329 (2014) Michael Goerz • Stanford/ARL • optimal control for entangling quantum gates



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Alternative: MCWF trajectories



 $\mathbf{\hat{H}} = \mathbf{\hat{H}}_1 + \mathbf{\hat{H}}_2 + i\kappa(\mathbf{\hat{a}}_1^{\dagger}\mathbf{\hat{a}}_2 - \mathbf{\hat{a}}_1\mathbf{\hat{a}}_2^{\dagger}), \quad \mathbf{\hat{L}} = \sqrt{2\kappa}(\mathbf{\hat{a}}_1 + \mathbf{\hat{a}}_2)$



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propagate with $\hat{\mathbf{H}}_{eff} = \hat{\mathbf{H}} - \frac{i\hbar}{2} \hat{\mathbf{L}}^{\dagger} \hat{\mathbf{L}}$, jump randomly with probability of $\|\Psi\|$



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- Cartan decomposition of any 4 × 4 unitary



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optimization for a perfect entangler

PE optimization for superconducting transmon qubits





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PE optimization for superconducting transmon qubits





optimization for a perfect entangler

PE optimization for superconducting transmon qubits





two transmon qubits with shared transmission line



two transmon qubits with shared transmission line



two transmon qubits with shared transmission line



optimal choice of parameters?

two transmon qubits with shared transmission line



optimal choice of parameters?



two transmon qubits with shared transmission line



optimal choice of parameters?



 \Rightarrow Goerz et al. arXiv:1606.08825 (2016).

hybrid optimization schemes

combine gradient-free and gradient-based optimization in multiple stages

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- ⇒ Faster convergence
- \Rightarrow Cleaner pulses



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Bridging the gap to experiment: spectral constraints, Hamiltonian estimation, noise source, ...

OCT: toolbox for quantum engineering

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- optimization methods
 - gradient-free
 - gradient-based: GRAPE, Krotov's method
summary

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 - gradient-based: GRAPE, Krotov's method
- applications
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 - robustness w.r.t. dissipation:
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 - design landscape explorations
 - bridging the gap to experiment: hybrid optimization schemes, filters

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Hideo Mabuchi Stanford





Kurt Jacobs ARL



github.com/mabuchilab/QNET

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Christiane Koch Kassel



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Felix Motzoi



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Thank you!